# Laith R. Sahawneh

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## Summary

- Research and development with thorough mathematical and probability background in the broad areas of autonomous systems with emphasis on **state estimation**, **localization**, **path planning**, collision detection and avoidance.
- Leadership role in agile development environments from technical concept development through implementation, testing and deployment using a wide range of software tools.
- Strong analytical, organizational and interpersonal skills.

#### Education

2011-2016

Brigham Young University
Ph.D. in Electrical and Computer Engineering

Provo, UT, USA GPA: 3.90/4.00

Dissertation: Airborne Collision Detection and Avoidance for Small UAS Sense and Avoid System

American University of Sharjah

Sharjah, UAE

2006-2009 M.Sc. in Mechatronics Engineering

GPA: 3.92/4.00

Thesis: Real-Time Implementation of GPS aided Low Cost Strapdown Inertial Navigation System

Yarmouk University

Irbid, Jordan

1997-2002 B.Sc. in Electronics Engineering

**GPA: 3.43/4.00** (#1 in class)

# Work Experience

04/2022 - present **TuSimple Inc**. (Autonomous Trucking Technologies)

100% Remote

# **Staff Autonomy Systems Engineer**

Defining detailed functional and performance requirements and driving cross-functional collaboration and analysis to
ensure the developed and implemented autonomous solutions are scalable, extensible and inline with product
requirements.

08/2017 - 04/2022 Motional AD Inc.

Pittsburgh, PA

# 10/2020 - 04/2022 Senior Research Scientist

Responsible for the full development cycle of the trajectories scoring and selection module from the design all the way to
writing production level C++ code, performance metrics formulation, testing & deployment on autonomous vehicles.

#### 09/2019 -10/2020 Research Scientist

 Design and implementation of behavior and decision making algorithms namely traffic signal and stop-sign controlled multi-way intersections, crosswalks and unprotected turns.

# 08/2017 -09/2019 Automated Driving Senior Engineer

Developed, and co-implemented, tested and deployed searching-based path planning algorithm.

### 02/2016-08/2017 University of Florida (UF Research & Engineering Education Facility/AFRL)

Shalimar, FL

Post-Doctoral Associate, Department of Mechanical and Aerospace Engineering

• Research and development of Graph-based cooperative localization and Extended Kalman Filter.

# 2011-2016 **Brigham Young University**

Provo, UT

**Graduate Research Assistant,** Department of Electrical and Computer Engineering

 Research and development of path planning, collision detection and avoidance algorithms for unmanned aircraft systems.

#### 2006-2011 Drake and Skull International PJSC

Abu Dhabi, UAE

Sr. Estimation Electrical Engineer

## 2004-2006 Ellipse A/S

Abu Dhabi, UAE

Electrical Engineer

#### May-Dec. 2003 Jordan University of Science and Technology

Irbid, Jordan

Cairo, Egypt

#### Software Skills

- Experience in building production level C++ software in Linux (Ubuntu) environments.
- Experienced with MATLAB and Simulink.
- Fair knowledge of Python software development.
- Wide-range use of cross-platform IDEs (e.g. CLion).
- Experienced in using LaTeX, and version control software (e.g. git).
- Fair knowledge of Model-Based System Engineering software modeling tools (e.g. Cameo and MagicDraw).

# **Teaching Experience**

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Fall 2015	Graduate Teaching Assistant, Feedback Control of Dynamic Systems (EC	En 483/ ME 431) <b>BYU, Provo</b>	
	<ul> <li>Provide assistance and guidance for students in lab projects both analytical solutions and Matlab/Simulink demonstration.</li> </ul>		
Fall 2008/09	<ul> <li>Graduate Teaching Assistant, Mechatronics Design Lab (MTR 590)</li> <li>Supervised mechatronics projects for 10 students, office hours, assignment</li> </ul>	American University of Sharjah, UAE ent grading and solutions.	
Fall 1998/99	<ul> <li>Undergraduate Teaching Assistant, Theory of Semiconductors (EE 246)</li> <li>Teach class tutorials for 30-45 students.</li> </ul>	Yarmouk University, Jordan	

# **Internship** 2001-2002

July-Oct. 2001	France Telecom Long Distance (FTLD)	Herndon, VA

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# **Professional Activities and Services**

- Member of IEEE.
- IEEE-Eta Kappa Nu (IEEE-HKN) / IEEE Young Professionals.
- IEEE Aerospace and Electronics Society (AESS).

**Egyptian Telephone Company (Quicktel)** 

- Member of AIAA.
- Professional Member of Institute of Navigation (ION).
- Four conference talks, 2 proposals, and 30+ paper reviews.
- Named an Excellent Reviewer for the Journal of Guidance, Control, and Dynamics twice for the years 2016 and 2017.

### **Publications**

• For the full list of my publications, please refer to my Google scholar link here.